

1+1+2 Covariant Approach to Gravitational Lensing in $f(R)$ gravity

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Why Fourth Order Gravity?

- ***Early Motivation:***
 - To question Einstein's GR [Weyl 1918, Eddington 1923]
 - Account for GR's limitations at high energy regimes [Starobinsky 1980]
- ***Contemporary Motivation:***

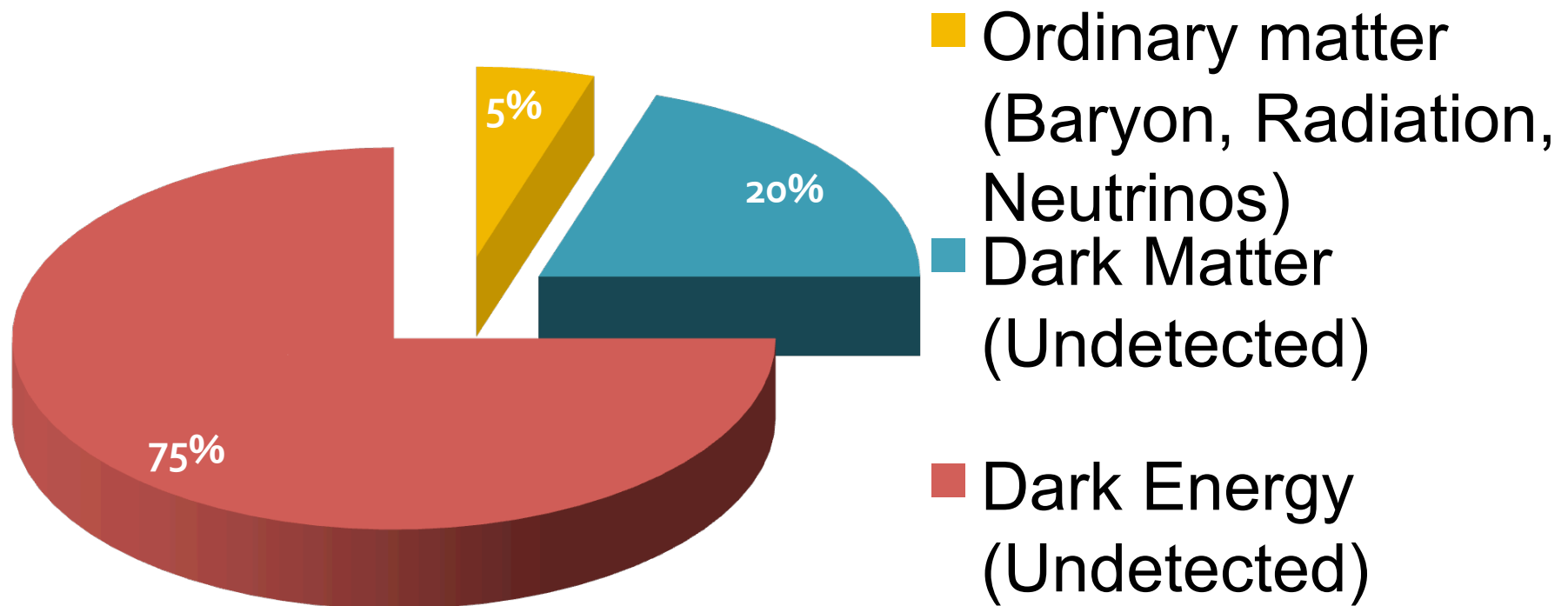
Observational evidence:

 - CMB
 - S_{nl}a
 - Weak Lensing

Why Fourth Order Gravity?

Observational evidence:

Flat, accelerating universe driven by a negative pressure component – *dark energy*



Why Fourth Order Gravity?

Einstein's GR

- Cosmological Constant Λ model (Dark Energy) + CDM = Λ CDM Universe (flat & homogenous)
- Quintessence
- Incomplete! Coincidence problem + Discrepancy in Λ value

Modified Gravity

- Geometric origin for dark energy
- Proposals: brane world theories, higher order curvature invariants \rightarrow *fourth order gravity*

Why Fourth Order Gravity?

$f(R)$ class of models:

- Fourth order theory of gravity
- Must account for observational tests like *bending of light* corresponding to:
 - Null geodesics
 - Knowledge of physically viable spherically symmetric solutions as in GR

Fourth order gravity

- $f(R)$ class of models can be derived from the classical action:

$$A = \frac{1}{2} \int d^4x \sqrt{-g} [f(R) + 2\mathcal{L}_m]$$

Fourth order gravity

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General function of curvature R

Fourth order gravity

- $f(R)$ class of models can be derived from the classical action:

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Standard matter term

Fourth order gravity

- $f(R)$ class of models can be derived from the classical action:

$$A = \frac{1}{2} \int d^4x \sqrt{-g} [f(R) + 2\mathcal{L}_m]$$

- Varying the action with respect to the metric gives the following field equations:

$$f' G_{ab} = f' \left(R_{ab} - \frac{1}{2} g_{ab} R \right) = T_{ab}^m + \frac{1}{2} g_{ab} (f - Rf') + \nabla_b \nabla_a f' - g_{ab} \nabla_c \nabla^c f'$$

- where

$$G_{ab} = \tilde{T}_{ab}^m + T_{ab}^R = T_{ab}^{tot},$$

$$f = f(R),$$

$$f' = \frac{df(R)}{dR}$$

Fourth order gravity

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4th order gravity as standard GR in the presence of two effective fluids.

1+3 Covariant Approach

- Space-time as an **ideal fluid** with a 1+3 threading of the manifold
 - w.r.t **time-like** congruence e.g., the fluid flow of galaxy cluster in cosmology or any fluid flow in astrophysics or cosmology.
 - and remaining 3-D **spatial** freedom. [Ehlers 1961, Ellis 1971]
- Gives general set of equations based on Ricci and Bianchi identities.
- Physical covariant variables with easy interpretation for co-moving observers.

1+3 Covariant Approach

- From the time-like flow u^a we construct the projection onto 3-D surfaces orthogonal to the flow: $h_{ab} = g_{ab} + u_a u_b$; $u^a u_a = -1$
- Covariant convective derivative : $\dot{T}_{c\dots d}^{a\dots b} = u^e \nabla_e T_{c\dots d}^{a\dots b}$
- Spatial covariant derivative:

$$D_e T_{c\dots d}^{a\dots b} = h_e^f h_g^a \dots h_h^b h_c^i \dots h_d^j \nabla_f T_{i\dots j}^{g\dots h}$$
- Kinematics of u^a gives information about the space-time geometry.

$$\nabla_a u_b = \underbrace{-u_a \dot{u}_b}_{\text{acceleration}} + \frac{1}{3} \underbrace{\Theta h_{ab}}_{\text{expansion}} + \underbrace{\sigma_{ab}}_{\text{shear}} + \underbrace{\omega_{ab}}_{\text{vorticity}}$$

acceleration expansion shear vorticity

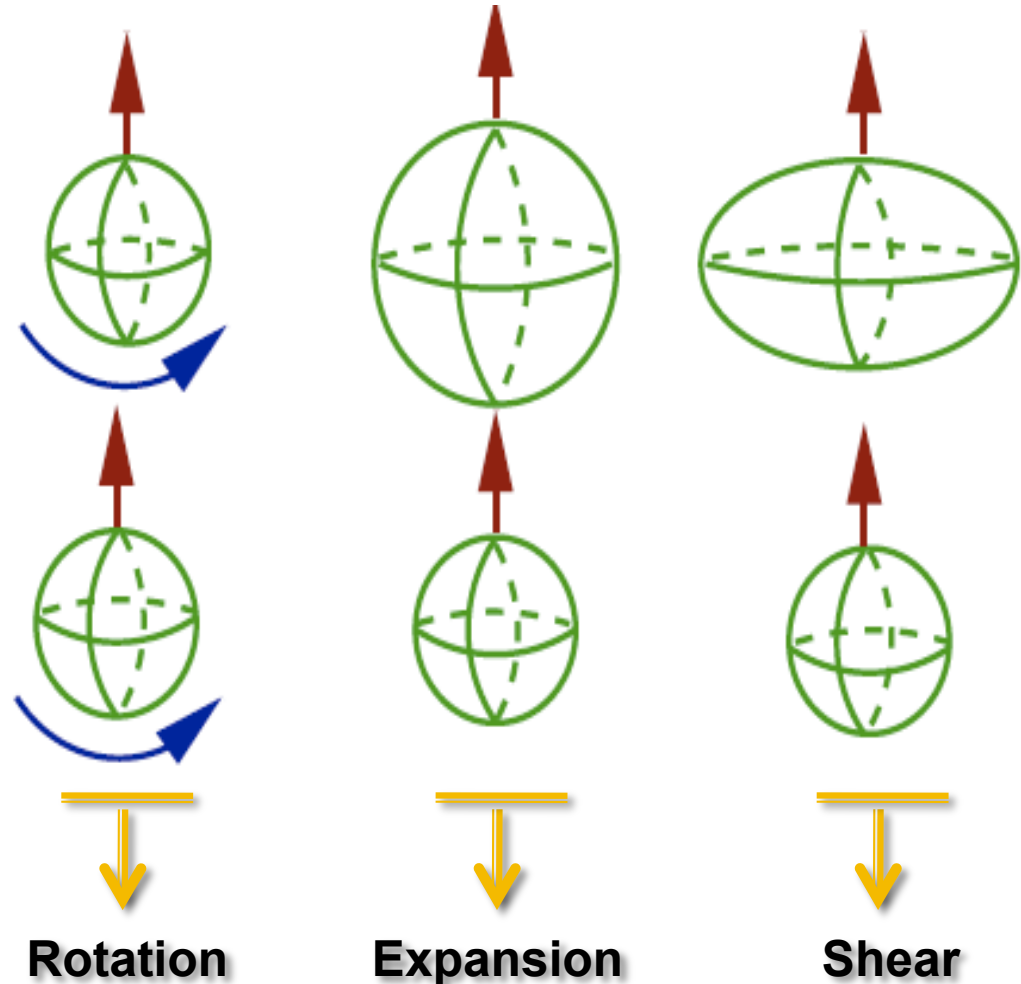
1+3 Covariant Approach

Ideal fluid flow:



Observer rest space

Kinematic effects:



Effective Thermodynamics

- The **total energy-momentum tensor** (EMT) is:

$$T_{ab}^{tot} = T_{ab}^m + T_{ab}^R$$

where

- T^m is the **matter** EMT
- T^R is the **curvature** EMT

$$T_{ab}^R = \frac{1}{2} g_{ab} (f - Rf') + \nabla_b \nabla_a f' - g_{ab} \nabla_c \nabla^c f'$$

Effective Thermodynamics

- The **total EMT** can be decomposed as usual relative to u^a giving:

$$T_{ab}^{tot} = \underbrace{\mu^{tot}}_{\downarrow} u_a u_b + \underbrace{p^{tot}}_{\downarrow} h_{ab} + \underbrace{2q_{(a}^{tot}}_{\downarrow} u_{b)} + \underbrace{\pi_{ab}^{tot}}_{\downarrow}$$

Energy density

Scalar pressure

Energy flux

Anisotropic pressure

$$\mu^{tot} = T_{ab}^{tot} u^a u^b = \tilde{\mu}^m + \mu^R,$$

$$q_a^{tot} = -T_{bc}^{tot} h_a^b u^c = \tilde{q}_a^m + q_a^R,$$

$$p^{tot} = \frac{1}{3} T_{ab}^{tot} h^{ab} = \tilde{p}^m + p^R,$$

$$\pi_{ab}^{tot} = -T_{cd}^{tot} h_{<a}^c h_{b>}^d = \tilde{\pi}_{ab}^m + \pi_{ab}^R.$$

$$\sim \Rightarrow \frac{1}{f'}$$

Effective Thermodynamics

- where the **total thermodynamic quantities** are:

$$\mu^{tot} = \frac{1}{f'} \left[\mu^m + \frac{1}{2} (Rf' - f) + f''' D^a R D_a R + f'' D^2 R - \Theta f'' \dot{R} \right],$$

$$p^{tot} = \frac{1}{f'} \left[p^m + \frac{1}{2} (f - Rf') - \frac{2}{3} f'' D^2 R - \frac{2}{3} f''' D^a R D_a R \right. \\ \left. + \frac{2}{3} \Theta f'' \dot{R} + f''' \dot{R}^2 + f'' \ddot{R} - \dot{u}_c (\nabla^c f') \right],$$

$$\pi_{ab}^{tot} = \frac{1}{f'} \left[\pi_{ab}^m + f''' D_{<a} R D_{b>} R + f'' D_{<a} D_{b>} R - \sigma_{ab} \dot{f}' \right],$$

$$q_{ab}^{tot} = -\frac{1}{f'} \left[q_{ab}^m + f''' \dot{R} D_a R + f'' D_a \dot{R} - \frac{1}{3} \Theta f'' D_a R \right].$$

Null geodesics

- Light propagates as null geodesics
- **Null tangent vector** k^a

$$k^a k_a = 0, \quad \frac{\delta k^a}{\delta v} = k^b \nabla_b k^a = 0$$

- Light propagation is received in the direction determined by unit spatial vector n^a

$$n^a n_a = 1, \quad n^a u_a = 0$$

- k^a is split as: $k^a = E(u^a + n^a)$
- where $E = -u_a k^a$: **energy associated with the rays**

1+1+2 Covariant Approach

- Involves 1+1+2 splitting of space-time into the time direction u^a and a further slicing of space into a **preferred direction** e^a and **sheet** [Clarkson & Barrett 2003]

$$e^a e_a = 1, \quad e_a u^a = 0.$$

- The projection onto the 2-D sheet,

$$N_a^b = h_a^b - e^b e_a = h_a^b + u^b u_a - e^b e_a$$

orthogonal to e^a and u^a

$$u^a N_{ab} = e^a N_{ab} = 0$$

1+1+2 Covariant Approach

- Spatial derivatives:
 - derivative in the e^a direction:

$$\hat{\psi}_{a\dots b}{}^{c\dots d} = e^e D_e \psi_{a\dots b}{}^{c\dots d}$$

- projected derivative onto the sheet:

$$\delta_e \psi_{a\dots b}{}^{c\dots d} = N_e^j N_a^f \dots N_b^g N_h^c \dots N_i^d D_j \psi_{f\dots g}{}^{h\dots i}$$

- Spatial derivative of e^a results in new variables:

$$D_a e_b = -e_a \dot{u}_b + \frac{1}{2} \phi N_{ab} + \xi \varepsilon_{ab} + \zeta_{ab}$$

acceleration (expansion shear vorticity of the sheet)

Dynamics

- Irreducible set of variables:

$$\left\{ \Theta, \mathcal{A}, \Omega, \Sigma, \phi, \xi, \mathcal{E}, \mathcal{H}, \mathcal{A}^a, \Omega^a, \Sigma^a, \alpha^a, a^a, \mathcal{E}^a, \mathcal{H}^a, \Sigma_{ab}, \zeta_{ab}, \mathcal{E}_{ab}, \mathcal{H}_{ab} \right\}$$

together with:

$$\left\{ \mu^{tot}, p^{tot}, Q^{tot}, \Pi^{tot}, Q_a^{tot}, \Pi_{ab}^{tot} \right\}$$

wholly characterize the space-time.

- The dynamical equations constitute those from decomposition of the 1+3 equations + dynamical equations for kinematic variables.

LRS Spacetimes

- **Locally rotationally symmetric** space-times (LRS), exhibit locally a unique preferred spatial direction constituting a local axis of symmetry
- The **kinematical & thermodynamic** variables $\{ \mathcal{A}, \Theta, \phi, \Sigma, \Omega, \mathcal{E}, \mathcal{H}, \mu^{tot}, p^{tot}, Q^{tot}, \Pi^{tot} \}$ fully describe LRS space-times
- The space-times are **isotropic** and therefore all the vector and tensor 1+1+2 variables are zero.

LRS Spacetimes

- **LRS class II:**

- admit spherically symmetric solutions
- vanishing vorticity Ω, ξ and consequently magnetic Weyl curvature H , vanishes

$$\left\{ \mathcal{A}, \theta, \phi, \Sigma, \mathcal{E}, \mu^{tot}, \rho^{tot}, Q^{tot}, \Pi^{tot} \right\}$$

LRS

Propagation equations

$$\begin{aligned}\hat{\phi} &= -\frac{1}{2}\phi^2 + \left(\frac{1}{3}\Theta + \Sigma\right) \left(\frac{2}{3}\Theta - \Sigma\right) - \frac{2}{3}\mu - \frac{1}{2}\Pi - \mathcal{E}, \\ \hat{\Sigma} - \frac{2}{3}\hat{\Theta} &= -\frac{3}{2}\phi\Sigma - Q, \\ \hat{\mathcal{E}} - \frac{1}{3}\hat{\mu} + \frac{1}{2}\hat{\Pi} &= -\frac{3}{2}\phi \left(\mathcal{E} + \frac{1}{2}\Pi\right) + \left(\frac{1}{2}\Sigma - \frac{1}{3}\Theta\right) Q.\end{aligned}$$

■ LRS c

- adm
- vani
- mag

Evolution equations

$$\begin{aligned}\dot{\phi} &= -\left(\Sigma - \frac{2}{3}\Theta\right) \left(\mathcal{A} - \frac{1}{2}\phi\right) + Q, \\ \dot{\Sigma} - \frac{2}{3}\dot{\Theta} &= -\mathcal{A}\phi + 2\left(\frac{1}{3}\Theta - \frac{1}{2}\Sigma\right)^2 + \frac{1}{3}(\mu + 3p) - \mathcal{E} + \frac{1}{2}\Pi, \\ \dot{\mathcal{E}} - \frac{1}{3}\dot{\mu} + \frac{1}{2}\dot{\Pi} &= \left(\frac{3}{2}\Sigma - \Theta\right) \mathcal{E} + \frac{1}{4}\left(\Sigma - \frac{2}{3}\Theta\right) \Pi \\ &\quad + \frac{1}{2}\phi Q - \frac{1}{2}(\mu + p) \left(\Sigma - \frac{2}{3}\Theta\right).\end{aligned}$$

Propagation/Evolution Equations

$$\begin{aligned}\dot{\mu} + \hat{Q} &= -\Theta(\mu + p) - (\phi + 2\mathcal{A})Q - \frac{3}{2}\Sigma\Pi, \\ \hat{Q} + \hat{p} + \hat{\Pi} &= -\left(\frac{3}{2}\phi + \mathcal{A}\right)\Pi - \left(\frac{4}{3}\Theta + \Sigma\right)Q - (\mu + p)\mathcal{A}, \\ \hat{\mathcal{A}} - \hat{\Theta} &= -(\mathcal{A} + \phi)\mathcal{A} + \frac{1}{3}\Theta^2 + \frac{3}{2}\Sigma^2 + \frac{1}{2}(\mu + 3p),\end{aligned}$$

Commutation relations

$$\hat{\dot{\psi}} - \dot{\hat{\psi}} = -\mathcal{A}\dot{\psi} + \left(\frac{1}{3}\Theta + \Sigma\right)\dot{\psi}.$$

LRS Spacetimes

- **LRS class II:**

- admit spherically symmetric solutions
- vanishing vorticity Ω, ξ and consequently magnetic Weyl curvature H , vanishes

$$\left\{ \mathcal{A}, \theta, \phi, \Sigma, \mathcal{E}, \mu^{tot}, p^{tot}, Q^{tot}, \Pi^{tot} \right\}$$

- **Static conditions:** expansion Θ , consequently shear Σ and heat flux Q

$$\left\{ \mathcal{A}, \phi, \mathcal{E}, \mu^{tot}, p^{tot}, \Pi^{tot} \right\}$$

- **Vacuum conditions:**

$$\left\{ \mathcal{A}, \phi, \mathcal{E}, \mu^R, p^R, \Pi^R \right\}$$

LRS Spacetimes

■ Propagation equations

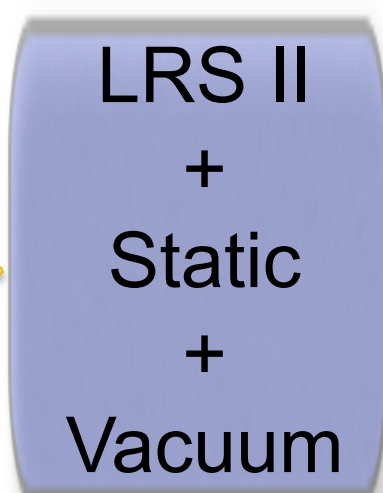
$$\hat{\phi} = -\frac{1}{2}\phi^2 - \frac{2}{3}\mu^R - \frac{1}{2}\Pi^R - \varepsilon,$$

$$\hat{\varepsilon} - \frac{1}{3}\hat{\mu}^R + \frac{1}{2}\hat{\Pi} = -\frac{3}{2}\phi\left(\varepsilon + \frac{1}{2}\Pi^R\right),$$

$$0 = -\mathcal{A}\phi + \frac{1}{3}(\mu^R + 3p^R) - \varepsilon + \frac{1}{2}\Pi^R,$$

$$\hat{p}^R + \hat{\Pi}^R = -\left(\frac{3}{2}\phi + \mathcal{A}\right)\Pi^R - (\mu^R + p^R)\mathcal{A},$$

$$\hat{\mathcal{A}} = -(\mathcal{A} + \phi)\mathcal{A} + \frac{1}{2}(\mu^R + 3p^R)$$



LRS II
+
Static
+
Vacuum

LRS Spacetimes

- μ^R , p^R , and Π^R are defined:

$$\mu^R = \frac{1}{f'} \left[\frac{1}{2} (Rf' - f) + f''\hat{X} + f''X\phi + f'''X^2 \right],$$

$$p^R = \frac{1}{f'} \left[\frac{1}{2} (f - Rf') - \frac{2}{3} f''\hat{X} - \frac{2}{3} f''X\phi - \frac{2}{3} f'''X^2 - \mathcal{A}f''X \right],$$

$$\Pi^R = \frac{1}{f'} \left[\frac{2}{3} f'''X^2 + \frac{2}{3} f''\hat{X} - \frac{1}{3} f''X\phi \right].$$

- where $X = \hat{R}$

Static spherically symmetric solutions

- The space-time is determined by the scalar functions R, χ, Φ, A
- To find solutions to R, χ, Φ, A we include the propagation equations in the direction of e^a :

$$f' \left[\hat{\phi} + \phi \left(\frac{1}{2} \phi - \mathcal{A} \right) \right] = \frac{1}{3} R f' - \frac{2}{3} f + f'' \chi (\phi + 2\mathcal{A}),$$

$$f' \left[\hat{A} + \mathcal{A} (\mathcal{A} + \phi) \right] = \frac{1}{6} f - \frac{1}{3} R f' - f'' \chi \mathcal{A},$$

$$\hat{R} = \chi,$$

$$f'' \hat{\chi} = -\frac{1}{3} R f' + \frac{2}{3} f - f''' \chi^2 - \chi (\phi + \mathcal{A}) f''.$$

Trace
equation

Static spherically symmetric solutions

Covariant results for spherically symmetric system:

- *Condition for existence of solutions with vanishing Ricci scalar:*

Imposing $|f'(0) < +\infty|$, $|f''(0) < +\infty|$, $|f'''(0) < +\infty|$, $f(0) = 0$ & $R = 0$

- $f'(0) = 0$: Propagation equations are identically satisfied for all \mathcal{A} and Φ that guarantees $R = 0$ and hence $X = 0$
 - For models with a vanishing Ricci scalar in GR will be a solution to the system.
 - Fourth order gravity solutions = **GR solutions + additional** e.g. Reissner Nordstrom

Static spherically symmetric solutions

Covariant results for spherically symmetric system:

- **Condition for existence of solutions with constant curvature**

Imposing $R = R_0 = \text{const} \Rightarrow X, \hat{X} = 0$

$$f_0' \left[\hat{\phi} + \phi \left(\frac{1}{2} \phi - \mathcal{A} \right) \right] = \frac{1}{3} R_0 f_0' - \frac{2}{3} f_0,$$

$$f_0' \left[\hat{\mathcal{A}} + \mathcal{A} (\mathcal{A} + \phi) \right] = \frac{1}{6} f_0 - \frac{1}{3} R_0 f',$$

$$0 = -R_0 f_0' + 2f_0. \quad \rightarrow \text{Barrow \& Ottewill (1983)}$$

- Solution iff
 - $f_0' \neq 0, f_0 \neq 0, 2f_0 - R_0 f_0' = 0$
 - $f_0' \neq 0, f_0 = 0, 2f_0 - R_0 f_0' = 0$ (Schwarzschild)
 - $f_0' = 0, f_0 = 0, R = R_0$

Static spherically symmetric solutions

Covariant results for spherically symmetric system:

- *The curious case of R^2 gravity*
 - It is expected from $2f(R_0) - R_0 f'(R_0) = 0$ that the conditions for constant curvature connects with universal constants
 - Local constant of integration is obtained here instead for R^2 Schwarzschild/Ads space-time
 - Implies *two bodies behaving as different Schwarzschild/Ads objects with different constant values can't have their masses determined uniquely just by studying their geodesics*

Static spherically symmetric solutions

Coordinate system relation

- Define hat derivative $\hat{M} = \frac{1}{2} r \phi \frac{dM}{dr}$

- Specialize choice of equations to $f(R) = R^n$

$$\frac{1}{2} nr \phi \frac{d\phi}{dr} R^{n-1} = \left(\mathcal{A} - \frac{1}{2} \phi \right) \phi R^{n-1} + \frac{n-2}{3n} R^n + (n-1) R^{n-1} X(\phi + 2\mathcal{A}),$$

$$\frac{1}{2} nr \phi \frac{d\mathcal{A}}{dr} R^{n-1} = -(\mathcal{A} + \phi) \mathcal{A} R^{n-1} + \frac{1-2n}{6n} R^n - (n-1) R^{n-2} X\mathcal{A},$$

$$\frac{1}{2} r \phi \frac{d\mathcal{R}}{dr} = X,$$

$$\frac{1}{2} nr \phi (n-1) \frac{dX}{dr} R^{n-2} = \frac{2-n}{3} R^n - n(n-1)(n-2) R^{n-3} X^2.$$

Static spherically symmetric solutions

Exact R^n solutions:

- **Schwarzschild solution:**
 - $R=0, dR/dr=0$, gives usual Schwarzschild coordinates iff $n=1,2,>3$
- **Solution with constant non-zero R :**
 - Substitute $X=0, R=R_0 \neq 0$ gives a solution iff $n=2$

Static spherically symmetric solutions

- **Solution with non-constant Ricci scalar non-vanishing at infinity:**

- From the ansatz: $\phi = \sqrt{C_1 r^\alpha + C_2 r^\beta}$, $R = C_3 / r^\gamma$ ($\gamma > 0$)
- We get (provided $n < (1 + \sqrt{3})/2$ and for $n \in (1, (1 + \sqrt{3})/2)$ n is an even rational number)

$$A = \frac{-C(5-4n)r^{-1-\frac{5-4n}{2-n}} + (2n-2)(2n-1)r^{-1+\frac{(2n-2)(2n-1)}{2-n}}}{2(2-n)\left(Cr^{-\frac{5-4n}{2-n}} + r^{\frac{(2n-2)(2n-1)}{2-n}}\right)} \sqrt{\frac{(1+2n-2n^2)(7-10n+4n^2)}{(2-n)^2\left(1+Cr^{-\frac{7-10n+4n^2}{2-n}}\right)}}; \quad \phi = \frac{2}{r \sqrt{\frac{(1+2n-2n^2)(7-10n+4n^2)}{(2-n)^2\left(1+Cr^{-\frac{7-10n+4n^2}{2-n}}\right)}}}$$

$$R = \frac{6n(n-1)}{[2n(n-1)-1]r^2}; \quad X = -\frac{12n(n-1)}{[2n(n-1)-1]r^3 \sqrt{\frac{(1+2n-2n^2)(7-10n+4n^2)}{(2-n)^2\left(1+Cr^{-\frac{7-10n+4n^2}{2-n}}\right)}}}$$

Static spherically symmetric solutions

- Solving for the metric definitions of the

covariant scalars: $\mathcal{A} = \frac{1}{2A(r)} \frac{dA}{dr} \sqrt{B(r)}, \quad \phi = \frac{2}{r} \sqrt{B(r)}$

$A(r)$ and $B(r)$ are from the metric:

$$ds^2 = -A(r)dt^2 + B(r)dr^2 + r^2(d\vartheta^2 + \sin^2\vartheta d\phi^2)$$

- Gives the solution (also found by T. Clifton 2006):

$$A(r) = r^{\frac{(2n-2)(2n-1)}{(2-n)}} + \frac{C}{r^{\frac{(5-4n)}{(2-n)}}}; \quad \frac{1}{B(r)} = \frac{(2-n)^2}{(7-10n+4n^2)(1+2n-2n^2)} \left(1 + \frac{C}{r^{\frac{(7-10n+4n^2)}{(2-n)}}} \right)$$

General form of Lensing Angle

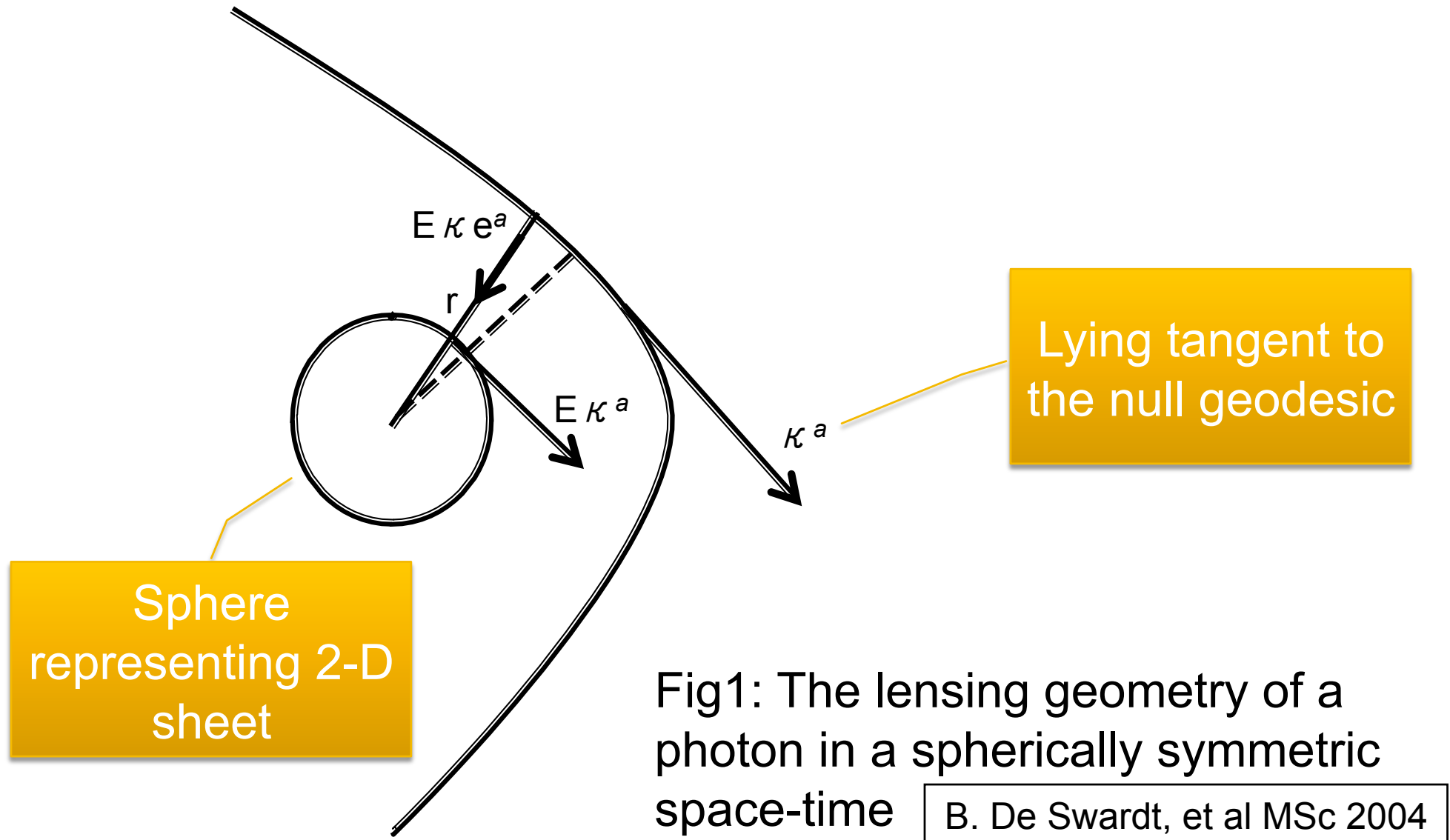
- Consider now the geometry of a null congruence using the 1+1+2 formalism.
- The kinematics are based on a **null vector** k^a which can be split as

$$k^a = E(u^a + \kappa e^a + \mathcal{K}^a)$$

- where E (*energy of ray*) and κ (*magnitude of radial component*) are the **lensing variables**
- The derivative in the k^a direction is defined

$$f' = k^a \nabla_a f \quad \text{with} \quad f' = E\mathcal{K}\hat{f}$$

General form of Lensing Angle



General form of Lensing Angle

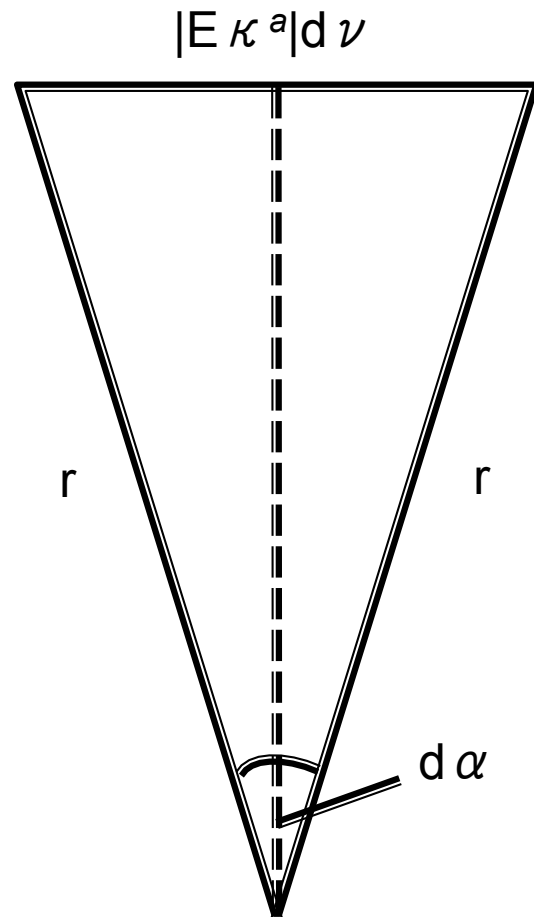


Fig2: geometry of the deflection angle

General form of Lensing Angle

- The **general form** of the deflection angle is given as

$$\alpha = \int_{v_1}^{v_2} \frac{1}{r} |E| \sqrt{1 - \kappa^2} dv - \alpha_0$$

for any form of gravity

- From:
 - the propagation equations of E and κ (*in static LRS II conditions*): $E' = -E^2 \mathcal{A} \kappa$,

$$\kappa' = E(1 - \kappa^2) \left(\frac{1}{2} \phi - \mathcal{A} \right)$$

- the solution to \mathcal{A} and ϕ

Deflection Angle in $f(R)$

- The **deflection angle** :

$$\alpha = 2 \int_{r_0}^{r_*} L^{-1} \frac{J}{r^2} \left[r \frac{(4n^2 - 6n + 2)}{(n-2)} - J^2 \left(r^{-2} + Cr \frac{(4n^2 - 12n + 11)}{(n-2)} \right) \right]^{-\frac{1}{2}} dr - \pi$$

- where:

$$J = \left[\frac{\frac{3(2n-3)}{r_0^{n-2}}}{\frac{-4n^2 + 10n - 7}{r_0^{n-2}} + C} \right]^{\frac{1}{2}} ; \quad L = \sqrt{\frac{(n-2)^2}{(1+2n-2n^2)(7-10n+4n^2)}}$$

Observables

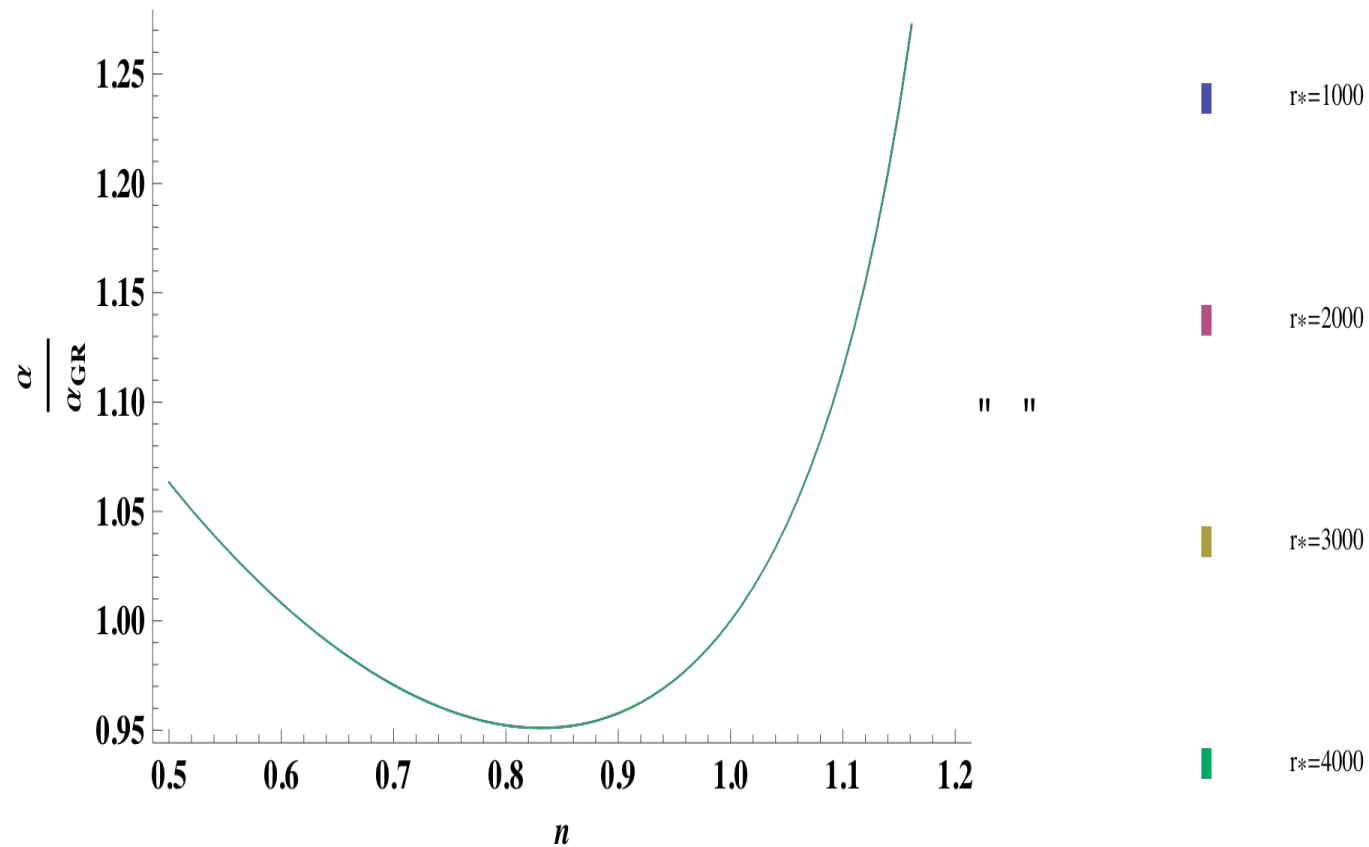


Fig3: plot of comparative bending angle vs n for various distances from source

Observables

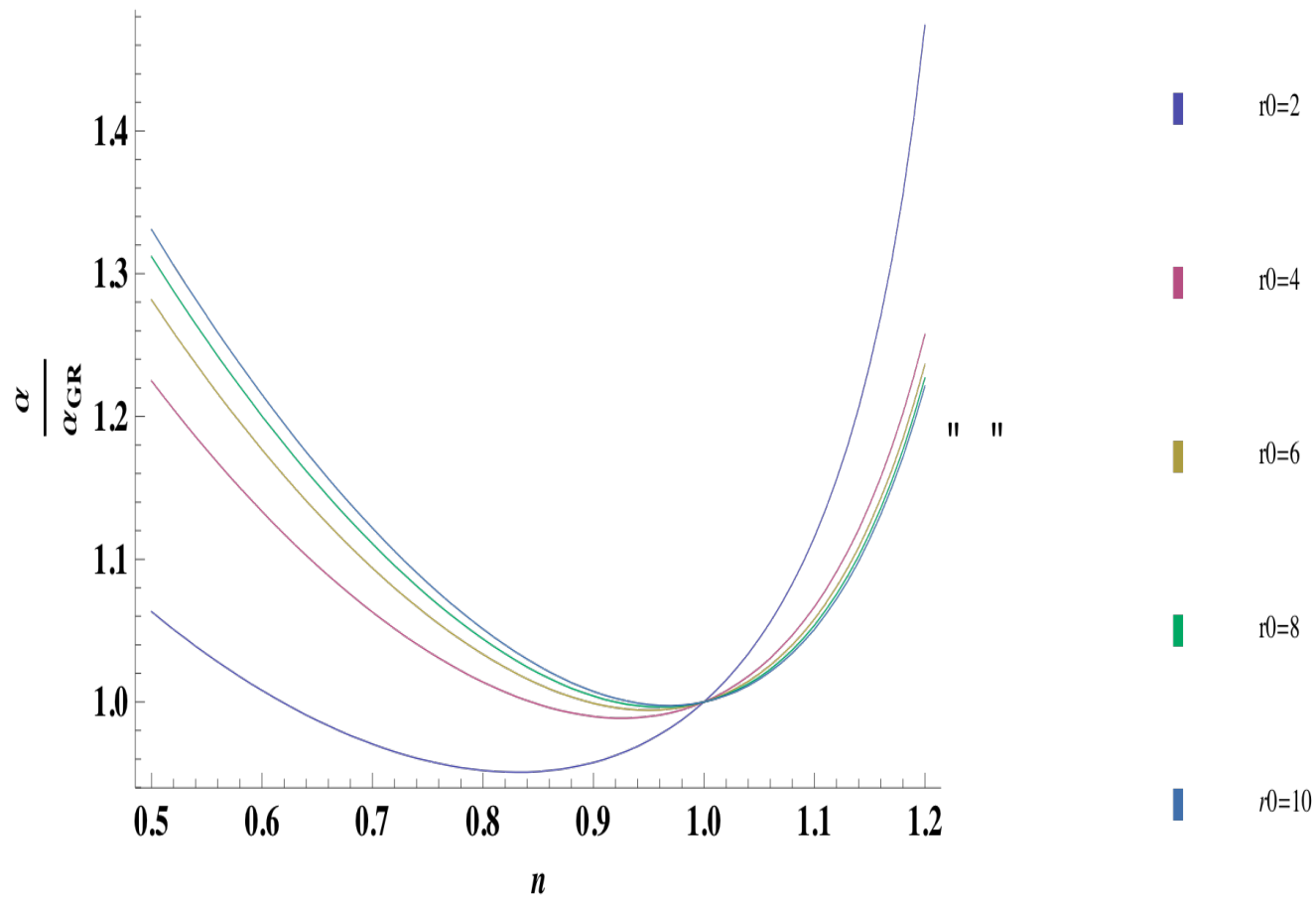


Fig4: plot of comparative bending angle vs n for various distances of closest approach

Conclusion

- *The deflection angle from the metric approach:*

$$\alpha = \int_{r_0}^{r_*} \frac{(AB)^{1/2} dr}{r \sqrt{(r/r_0)^2 B(r_0) - B(r)}} - \pi$$

- *Advantage of the covariant approach:*
 - Applies to any LRS space-time whilst metric applies only to spherically symmetric space-times
 - Physically relevant quantities (the *kinematic & dynamic variables & their propagation equations*) manifesting the underlying physics for better understanding

Conclusion

- A set of master equations that provide important results and conditions for spherically symmetric static solutions in $f(R)$ gravity were derived [gr-qc/0908.3333]
 - A number of exact solutions were found from these equations for $f(R) = R^n \rightarrow$ indicative of Birkoff's theorem violation
- A covariant form of the bending angle for a particular solution was derived where more bending expected for R^n gravity model and could be used to obtain signatures for these models